

Arduino Powered Autonomous Heat and Flame Detection Robot

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Abstract: This paper presents the design and development of an Arduino-powered autonomous flame heat detection robot. The system is intended to enhance safety by detecting fire hazards at an early stage and responding quickly without human intervention. The robot is equipped with the flame sensors to identify fire sources, while Arduino Uno microcontroller processor the sensors data to make decision in real time. A motor driver and DC motors enable the robot to navigate autonomously towards the fire source ,and a small water pump is used to suppress the flames effectively .The autonomous operation reduces the human risk in hazards environments, making it suitable for use in homes, laboratories, and small industrial applications .The system is designed to be low-cost, energy-efficient and user-friendly ,which makes it practical choice for educational and safety demonstration purposes .Future enhancements of the paper could include IOT(Internet Of Things)for remote monitoring ,use of advanced sensors such as infrared and smoke detectors for higher accuracy ,and machine learning algorithms to improve navigation and fire detection capabilities.

Keywords: *Arduino UNO, Flame Sensor, Autonomous System, DC Motor, Water Pump, IOT, Fire Safety, Embedded System*

I. INTRODUCTION

Flame and heat detection are critical in early fire detection systems, especially in environments prone to fires. Traditional systems are static, and their sensors can miss certain hazards. This research presents an autonomous robot powered by Arduino that is capable of detecting flames and excessive heat, providing an immediate alert, and executing corrective actions such as activating a water pump for fire suppression. The robot's autonomous navigation ensures timely response to fire threats while maintaining safety in hazardous environments.

II. PROCEDURE FOR PAPER SUBMISSION

A. Review Stage

This study explored the feasibility of using Arduino as the microcontroller for a mobile, autonomous fire detection system. Various components, including flame sensors, a motor driver, and a pump, were integrated to achieve autonomous behavior.

B. Final Stage

The system was fully developed and tested with both flame detection and fire suppression functionalities. A thorough evaluation of the components was performed to ensure optimal performance, including reliability in detecting flames and heat under different conditions.

III MATH

The flame sensor output is directly proportional to the intensity of the flame radiation, as expressed by: $\text{Volt}\{\text{out}\} = k \times \text{Current (I) Frequency}(f)$ where $\text{Volt}\{\text{out}\}$ represents the sensor output voltage (in volts), $\text{Current(I) Frequency (F)}$ is the flame intensity, and k is the proportionality constant of the sensor. The threshold voltage $\text{Volt(V) Temperature(T)}$ is programmed in the Arduino to determine when the fire detection system should activate the buzzer and water pump $\text{Volt}\{\text{out}\} > \text{Volt(V) Temperature(T)}$, then the system triggers an alert and activates the extinguishing mechanism. The power consumed by the circuit is determined using the general electrical Equation $= V \times I$ where P is the electrical power in watts, V is the supply voltage in volts, and I is the current in amperes. These relations are essential for sensor calibration and efficient power management in the system.

IV UNITS

The measurements are expressed in the International System of Units (SI). The consistent use of SI units ensures standardization, accuracy, and ease of comparison in both design and performance analysis of the Arduino Powered Autonomous Heat and Flame Detection Robo.

A. Voltage and Power Level

The system primarily involves electrical, thermal, and mechanical parameters, which are measured in their respective SI base and derived units. The table below summarizes the major quantities and their corresponding units used throughout the paper. $P = V \times I$ Where P is the total power (in watts), V is the supply voltage (in volts), and I is the current (in amperes).

B. Temperature Measurement and Calibration

The flame sensor and optional heat sensor measure temperature changes in °C. The sensor values are converted to voltage and then mapped to temperature readings using the sensor's calibration equation.

C. Unit Consistency

Consistent use of SI units across all subsystems sensing, control, and actuation helps in reducing conversion errors and simplifies integration of additional modules in future upgrade.

V HELPFUL HINTS

A. Figures and Tables

Ensure that all figures and tables are clearly labeled and properly referenced in the text. Each figure should have a concise caption placed below it, while table captions should appear above the table. Use standard numbering such as "Fig. 1," "Fig. 2," etc., and refer to them in the text (e.g., as shown in Fig. 1). All units used in figures and tables must follow the SI system for consistency.

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All equations must be properly formatted and numbered sequentially. For example: $P = V \times I$
Use italics for variables (V , I , P) and ensure all symbols are defined immediately after their first appearance.

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IEEE papers generally use Times New Roman, 10-point font, in a two-column layout. Maintain proper spacing and alignment to ensure readability. Avoid decorative fonts or excessive text coloring.

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Keep your writing formal, concise, and technical. Avoid long sentences and unnecessary repetition. Use active voice whenever possible and define abbreviations the first time they appear.

F. Submission and Review

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Improper Use of Figures and Tables Figures and tables are powerful tools for representing data, but they are often misplaced or lack captions. Every figure must include a descriptive caption. **Formatting Errors** One of the most frequent mistakes is failing to follow the IEEE two-column format. Authors sometimes use incorrect font sizes, spacing, or margins, which makes the paper look inconsistent. Always use Times New Roman, 10-point font, with single spacing, and ensure alignment matches the IEEE template. **Improper Figure or Table Placement** Figures and tables should be positioned as close as possible to where they are first referenced in the text. A common mistake is placing all figures at the end of the document. Each figure must have a descriptive caption and should be clearly readable even when printed in gray scale. **Missing or Incorrect Units** Forgetting to include units for measured quantities (like voltage, temperature, or power) can lead to confusion. Always follow the SI unit system and include units in all calculations, tables, and graphs. **Unclear Equations** Equations that are not properly formatted or explained are difficult for readers to interpret. Every variable in an equation must be defined after its first appearance, and equations should be numbered sequentially for

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IX. CONCLUSION

This paper presented the design and implementation of an Arduino-powered autonomous heat and flame detection robot capable of detecting fire and responding immediately by activating an extinguishing mechanism. The system integrates a flame sensor, buzzer, TIP122 driver circuit, and a water pump, all controlled by an Arduino Uno. Through automation, the robot effectively detects fire sources and suppresses them within a short response time, minimizing human involvement and risk. The proposed system demonstrates a low-cost, energy-efficient, and reliable approach to fire detection and

prevention, especially in areas prone to accidental fires. The results show that using simple hardware components and open-source programming can create a practical safety solution adaptable to both domestic and industrial Environments. Future developments of this paper may include integration with IoT platforms, wireless communication modules, or machine-learning-based decision systems for enhanced fire prediction, remote monitoring, and improved accuracy. This advancement would make the system more intelligent, scalable, and useful in real-time safety Applications.

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